

# AUNT-SUE Research Symposium

## Capturing Fear of Crime: Mapping Local Knowledge



*13<sup>th</sup> January 2010 – 15:30 – 16:00*

[ EPSRC ]

AUNT-SUE CONSORTIUM

TOWARDS A SUSTAINABLE URBAN ENVIRONMENT | URBAN DESIGN + TRANSPORT | THEME: SOCIAL INCLUSION

# Capturing Fear of Crime: Mapping Local Knowledge

- Outline
  - Predicting Fear of Crime
  - Where do people feel scared?
  - Validating the Predictive Maps
  - Further Work

# Predicting Fear of Crime

- Prospect/Refuge Theory
  - The level of fear felt depends on two factors:
    - Prospect – how far ahead you can see and how wide is the view
    - Refuge – how many potential hiding places there are for people to jump out from

# Predicting Fear of Crime

- Street Environment Index
  - Combines elements of New Urbanism and Broken Windows Theory
    - Broken Windows: unrepaired broken windows lead to other broken windows as they are a sign that no one cares. The degeneration of an area leads to a withdrawal of people from the street, increasing the opportunity for crime

# Predicting Fear of Crime

- Street Environment Index
  - Combines elements of New Urbanism and Broken Windows Theory
    - New Urbanism: the presence of people on the street will deter criminals and reduce the opportunity for offending.

# Predicting Fear of Crime

- Both theories have been implemented in a GIS and the concept of Isovists used to generate surfaces to ‘predict’ locations of fear



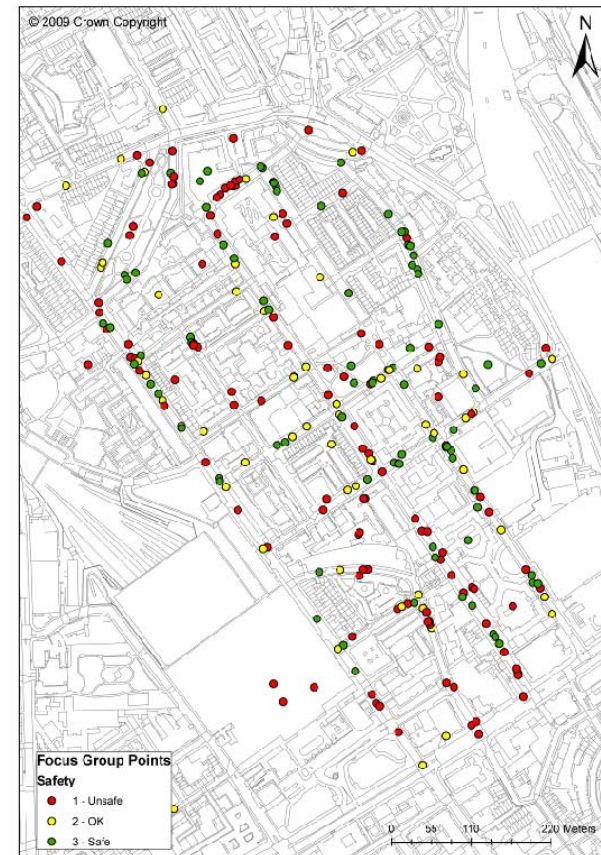
# Where do People Feel Scared?

- Four Focus Group sessions held with residents in Somers Town

Group	Number of Participants
Focus Group 1: Single Parents	6
Focus Group 2: Women under 27	4
Focus Group 3: Elderly	4
Focus Group 4: Bangladeshi men under 27	5 (excluded from analysis)

# Where do People Feel Scared?

- Each participant was asked to indicate on a map where they feel safe, neutral and scared
- Total of 182 valid points collected:
  - 90 'scared'
  - 43 'neutral'
  - 49 'safe'



# Where do People Feel Scared?

- Each participant was also asked, where appropriate, to participate in a walk-about in the area, during which they made comments on the local environment

# Where do People Feel Scared?

- An Inverse Distance Weighting Interpolation was used to create a ‘surface of fear’ as expressed by the Focus Group participants



# Where do People Feel Scared?

- Surface of Fear
  - Due to the uneven distribution of the Focus Group points, the map is rather patchy
  - Additionally, some contradictory cases were encountered, when one participant rated a location positively and another negatively
    - These were left as they reflect the view of the community

# Validating the Predictive Maps

- Reclassification
  - All three maps were reclassified into three classes using an equal-interval classification
  - The use of the equal-interval classification allows the resulting map to clearly highlight the range of ‘safe’, ‘neutral’ and ‘fearful’ areas on each map without being biased by the distribution of the data

# Validating the Predictive Maps

- Subtraction
  - The reclassified Focus Group surface was then subtracted from the reclassified SEI map and the reclassified Prospect/Refuge map
  - The results were analysed to identify areas of agreement and disagreement

# Validating the Predictive Maps

- SEI (New Urbanism and Broken Windows)
  - 45% match between the surfaces



# Validating the Predictive Maps

- SEI (New Urbanism and Broken Windows)
  - 24.64% match for negatively weighted areas
  - 18.15% match for neutral areas
  - 2.85% match for positive areas
- This may be due to the predominance of negative values on the FG Map:
  - 51% of FG surface was negative
  - 30% of SEI surface is negative

# Validating the Predictive Maps

- Prospect Refuge
  - 46% match between the surfaces



# Validating the Predictive Maps

- Prospect Refuge
  - 34% match for negatively weighted areas
  - 11.71% match for neutral areas
  - 0% match for positive areas
- This may be due to the predominance of negative values on the FG Map and on the P/R Map:
  - 51% of FG surface was negative, 30% neutral and 19% positive
  - 60% of P/R surface is negative, 39.8% neutral and 0.14% positive

# Validating the Predictive Maps

- In both cases, % match obtained is higher than would be obtained through a random process
- However, anecdotal evidence from the focus group participants highlights the importance of local knowledge:
  - “Fights between school boys”
  - “Very high density of people in the morning and between 3 and 3.30pm”
  - “Youths gather here and abuse passers-by”

# Further Work

- Current surface of fear generated by the Focus Groups is a bit ‘patchy’ – need to improve this by creating a combined map reflecting a consensus view for the community
- It is also possible to measure fear using avoidance behaviour – where do people not walk, even though it may provide the shortest route to their destination?
  - This could potentially be measured by using GPS traces of residents’ movements

# Further Work

- The mechanism used for the SEI is very flexible and features to represent ‘local knowledge’, with appropriate weightings, could also easily be added
- Need to investigate the importance of familiarity with an environment – do urban features become more important when you are a stranger to a location?

# Capturing Fear of Crime: Mapping Local Knowledge

Thank You – Any Questions?